lodel AC3337

Three-Axis Motion Simulator Model AC3337





The Series AC3337 Three-Axis Test Tables are part of an economic series of rate tables. The model allows testing of several medium Inertial Measurement Units (IMU's) or Micro Electro Mechanical Systems (MEMS) sensors simultaneously. The simulator is capable of simulating the roll, pitch and yaw motion of a vehicle in space.

The axes are driven by direct drive brushless motors. The brushless motors offer excellent torque and since they have no wear parts the reliability is excellent. AC drive amplifiers produce the required current to power the motors. The table features excellent instantaneous rate stability and precise, stable absolute positioning.

The pitch axis is equipped with a stow lock to facilitate the safe loading/unloading of the UUT. The yaw axis is vertical and supports the middle axis. The simulator is secured to the facility floor using leveling wedges.

Slipring capsules take the signals and or power from the table base to the device under test. ACUTRONIC offers three standard slipring packages for better economy.

The table is controlled by the ACUTROL®3000 digital controller. The controller has a touch sensitive display and a scalable analog input/output interface. Optionally, the standard digital interfaces of IEEE-488 and Ethernet (TCP/IP) can be supplemented with VMIC or SCRAMNet reflective memory interfaces. For more details, please refer to the ACUTROL®3000 datasheet.



Dimensions	Height, max Height of middle axis Width across middle axis Base dimension	mm mm mm	1810 1400 1390 1450 x 1450 (LxW) (turn diameter)
	Table top diameter Table top offset	mm mm	300 (20xM6 helicoils) 87
	Table top flatness	mm	0.05
Unit Under Test (UUT)	Payload weight Clearance envelope	kg mm	20 (nominal) 300 x 350 (ØxH)

Mech.	Roll Axis	Pitch A	Axis	Yaw Axis
specifications				
Orthogonality	+/-5"			+/-5"
Wobble	<5"	<5'	,	<5"
Static and dynamic				
performances				
Angular freedom	Continuous	Contin	uous	Continuous
Positioning accuracy	5 arcsec RSS	5 arcsed	RSS	5 arcsec RSS
Rate range	+/-1500°/s	+/-400)°/s	+/-400°/s
Acceleration, no load	1'500°/s ²	400°	/s ²	450°/s ²
with load	Load inertia dependent	Load inertia	dependent	450°/s ²

Slipring Configuration according to standard wiring schematics			
	Ways	Connectors	
Wiring Typ 1A	70 lines rated 2A, 150VDC	2x 37pin D-Sub	
Wiring Typ 2A	45 lines rated 2A, 150VDC	1x 50pin D-Sub	
	+10 lines rated 5A, 150VAC	1x 15pin D-Sub	
Wiring Typ 3A	45 lines rated 2A, 150VDC	1x 50pin D-Sub	
	+4 lines rated 20A, 400VDC	1x 5pin D-Sub (5W5)	

Options

- Standard (450mm) or customized (up to max. 450mm) table top (dynamic specification subject to change)
- RF (up to 18GHz) rotary joints for GPS signals
- Base template

Installation requirements

• 3 x400VAC +/-8% with ground (PE; no neutral required), 50/60Hz, 16Amps fused.

Packing details (approximate)

- Box 1 (simulator): 170x100x200cm (WxDxH), Grossweight: 735kg, Netweight: 500kg
- Box 2 (console): 85x100x235cm (WxDxH), Grossweight: 440kg, Netweight: 285kg

Delivery time

• 8 months average

Three-Axis Motion Simulator Model AC3337-TC



The Series AC3337-TC Three-Axis Test Tables are part of an economic series of rate tables.

The model allows testing of several medium Inertial Measurement Units (IMU's) or Micro Electro Mechanical Systems (MEMS) sensors simultaneously.

The axes are driven by direct drive brushless motors. The brushless motors offer excellent torque and since they have no wear parts the reliability is excellent. AC drive amplifiers produce the required current to power the motors. The table features excellent instantaneous rate stability and precise, stable absolute positioning.

The pitch axis is equipped with a stow lock to facilitate the safe loading/unloading of the UUT within the temperature chamber, cooled by the expansion of Carbon Dioxide CO₂ gas (-TCC) or Liquid Nitrogen (-TCN). The yaw axis is vertical and supports the middle axis. The simulator is secured to the facility floor using leveling wedges.

Slipring capsules take the signals and or power from the table base to the device under test. ACUTRONIC offers three standard slipring packages for better economy.

The table is controlled by the ACUTROL®3000 digital controller. For more details, please refer to the ACUTROL®3000 datasheet.



Dimensions	Height, max Height of middle axis Width across middle axis Base dimension Table top diameter Table top offset Table top flatness	mm mm mm mm mm mm	1810 1400 1390 1450 x 1450 (LxW) (turn diameter) 300 (20xM6 helicoils) 25 0.05
Unit Under Test (UUT)	Payload weight Clearance envelope	kg mm	20 (nominal) 300 x 240 (ØxH) inside chamber
Thermal Chamber	Temperature Range Cooling gradient Heating gradient Stability	degC degC/min degC/min degC	-55 / +100 -4 +4 +/-1.5

Mech. specifications	Roll Axis	Pitch Axis	Yaw Axis
Orthogonality	+/-5"		+/-5"
Wobble	<5"	<5"	<5"
Static and dynamic			
performances			
Angular freedom	Continuous	Continuous	Continuous
Positioning accuracy	5 arcsec RSS	5 arcsec RSS	5 arcsec RSS
Rate range	+/-1'500°/s	+/-400°/s	+/-400°/s
Acceleration, no load	1'500°/s ²	400°/s ²	400°/s ²
with load	Load inertia dependent	Load inertia dependent	400°/s ²

Slipring Configuration according to standard wiring schematics			
	Ways	Connectors	
Wiring Typ 1B	52 lines rated 2A, 150VDC	2x 37pin D-Sub	
Wiring Typ 2B	28 lines rated 2A, 150VDC	1x 50pin D-Sub	
	+10 lines rated 5A, 150VAC	1x 15pin D-Sub	
Wiring Typ 3B	28 lines rated 2A, 150VDC	1x 50pin D-Sub	
	+4 lines rated 20A, 400VDC	1x 5pin D-Sub (5W5)	

Options

- Customized (up to max. 300mm) table top (dynamic specification subject to change)
- RF (up to 18GHz) rotary joints for GPS signals
- Base template

Installation requirements

- 3 x400VAC +/-8% with ground (PE; no neutral required), 50/60Hz, 25Amps fused.
- LN₂ supply

Packing details (approximate)

Box 1 (simulator): 170x100x200cm (WxDxH), Grossweight: 755kg, Netweight: 520kg
 Rev 2 (see 25kg): 95x400x205 are (WxDxH). Grossweight: 460kg, Netweight: 205kg.

• Box 2 (console): 85x100x235cm (WxDxH), Grossweight: 460kg, Netweight: 305kg